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THE ING TIME SERVICE

REV 1.0

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OVERVIEW OF THE ING TIME SERVICE

The ING Time Service consists of the Central Time Service (CTS) located in the CLIP centre of the INT and the remote time service equipment in the WHT and JKT. These are connected back to the CTS via fibre optic cables. These fibre optic links are used for synchronisation and monitoring purposes.

The time service for each telescope consists of an RGO designed digital modular clock (*circa* 1982) based on CMOS logic controlled by a highly stable quartz crystal oscillator made by HCD Research Ltd. The time service provides both UTC (Universal Co-ordinated Time) and LST (Local Sidereal Time).

The time service for the INT is housed within the CTS. The WHT and JKT time services are installed in rack cabinets in the computer room (WHT) and the CLIP centre (first floor JKT)

Local sidereal time (LST) is required for telescope POINTING and TRACKING. However, it should be noted that <u>only</u> <u>UTC is supplied to the Telescope Control System (TCS) from the time service</u>. An algorithm within the telescope control software converts UTC to LST. The LST output from the time service is used to drive the LST time display wall boxes and thus serves only as a reference.

n.b. Since the time display wall boxes have been replaced with free standing digital UTC/LST clocks in each control room, the LST output from the RGO clocks is now redundant.

UTC time (hh:mm:ss), day number and the year (in BCD data format) together with selected UTC related frequencies are sent from the RGO digital clocks to the TCS DEC ALPHA computers via CAMAC.

The time service is powered from an ERSKINE constant potential battery charger. These are located in the electrical power intake rooms of each telescope building. The time service is connected directly across the battery bank (28v), the mains supply being used to float charge the batteries. If the mains charging fails, the batteries will keep the time service going for approx. 24 hrs. The mains supply for the ERSKINE unit itself comes from the local UPS, so the chances of a time service failing due to a power break is very remote.

It should be noted that most of the CTS is dedicated solely to the monitoring and calibration when needed of the RGO digital clocks. As these use free running quartz oscillators, errors in the order of milliseconds can build up over time due to crystal ageing.

With today's technology, the ING time service could be updated using a dedicated GPS system at each telescope. However, due to expenditure cutbacks and the considerable effort needed in software and hardware changes and the Time Service being deeply embedded into the TCS/CAMAC systems, I very much doubt if this will happen.

THE CENTRAL TIME SERVICE

The CTS is housed in two full height rack cabinets in the INT CLIP centre and contains:

Left hand cabinet (from the top down)

- WHARTON time display box (UTC)
- MARCONI digital counter-timer
- Time service distribution patch panel (BNC connectors)
- GOULD ADVANCE dual beam digital storage oscilloscope
- RADIOCODE GPS-8000 satellite controlled clock
- Storage shelf for log book , *etc*

Right hand cabinet (from the top down)

- SULZER frequency standard (used only for backup if GPS-8000 fails)
- The INT time service (RGO digital modular clock)

- Bank of four RGO built Linear Phase Recorders
- Bank of three RUSTRAC chart recorders
- DX300 HF radio receiver (used only for backup if GPS-8000 fails)

The drawing below shows the interconnections between the various units of the CTS.



Figure 1 ING Time Service interconnections

Wharton Time Display Box

This is connected to the Standard Time Distribution module (UTC) via a 9 pin connector on the rear of the INT time service. It uses an IRIG time signal and serves as a facility for testing other time display boxes used around the site. As these boxes have been replaced with free standing UTC/LST digital clocks in the control rooms, to all intents and purposes it is redundant.

MARCONI Digital Counter-Timer

This is used for displaying the instantaneous difference in milliseconds between the UTC reference (GPS-8000) and UTC(M) as measured from an RGO digital clock. The *start* signal is triggered from the rising edge of the UTC 1mS/Sec reference. The *stop* signal from the rising edge of the 1mS/Sec pulses from the selected RGO digital clock. These signals are available from the BNC connectors on the Time Service Patch Panel.

The rate of drift from an RGO digital clock can be followed on a regular basis and when the error exceeds a few milliseconds, it can be manually re-synchronised to bring it back into step with the GPS 8000 UTC reference.

To improve measurement accuracy, an external clock is used to drive the counter-timer. The 1MHz signal being taken directly from the INT RGO digital clock.

ING Time Service Patch Panel

This contains a row of BNC connectors allowing the 1mS/Sec pulses to be measured from any time service using the MARCONI counter or oscilloscope. Not all the BNC connectors are not used. The ones that are being:

GPS	8000			Reference	Signals f	rom ING time	e services
1Hz	1mS/Sec	100KHz	HF	UTC	INT	JKT	WHT
Raw	Processed	Phase ref	Signal	1mS/Sec	1mS/sec	1mS/Sec	1mS/Sec
signal	Signal *	link to	from	from GPS			
		LPR-2	HF Radio	*			

* Same signal

The UTC reference signal is left permanently connected to the A inputs of the counter and oscilloscope. It is just a simple matter of moving the BNC 'T' connector (going to the B inputs of the counter and oscilloscope) between the INT, JKT and WHT connectors to measure the time difference.

Dual beam digital storage oscilloscope

This is used in parallel with the MARCONI counter to measure the difference in UTC between the GPS8000 and RGO clocks. The 1mS/Sec pulse from the GPS-8000 is displayed on one trace with the oscilloscope triggered off the *rising* edge of this pulse. The 1mS/Sec signal from an RGO clock is display on the other beam. Due to the slow duration of the time base, the oscilloscope is best used in storage mode to see the events.

RADIOCODE GPS-8000 Satellite Controlled Clock

This is the heart of the ING Central Time Service and generates the UTC reference which is used to synchronise and calibrate the RGO digital clocks at each telescope.

The GPS-8000 contains a rubidium oscillator which in conjunction with GPS satellite correction, provides a highly stable and accurate long term time scale. The accuracy of UTC being in the order of ± -150 or better when tracking at least one satellite. The stability of the rubidium oscillator being better than 5 x 10⁻¹².

A small antenna mounted on the roof of the west side of the INT building receives the satellite signals at 1.023GHz. However, due to the screening effect of the dome, some satellites above the horizon may not be received. Reception from only one satellite is sufficient to *lock* the GPS-8000 to UTC. A visual inspection of the green status LED's: **Receiving Sat** and **Valid Time** will generally show all is working correctly.

In the rare case if no satellites are seen, the rubidium oscillator acts as a *flywheel* keeping UTC stable until a satellite is found. When this happens, corrections are made to the oscillator to compensate for any small changes that may have occurred in the mean time. These being in the order of < 50nS per hour.

Various menus can be selected using the front panel keypad. Menu 1 is usually selected as this provides the most useful information, *i.e.* The time in hh:mm:ss, day of year, *etc*

The GPS-8000 provides an output pulse of 1 second duration and is used to synchronise the WHT, INT and JKT digital clocks when needed. The *rising* edge of this pulse being taken as the UTC reference.

As well as supplying the time reference for UTC, the GPS 8000 also generates a 100KHz (50% duty cycle) phase reference TTL signal which is required for the Linear Phase Recorders.

Further information on the GPS-8000 can be found in the User's Manual keep in the filing cabinet near the CTS.

1mS/Sec PULSE GENERATOR

It should be noted that the TTL 1pps signal from the GPS-8000 has a 50% duty cycle. To produce the required 1mS/Sec synchronisation pulse, the signal is modified by passing it through a pulse generator which is simply a monostable (74LS123) circuit. The RC timing values have been selected to produce one second pulses of 1mS duration, the rising edge defining the start of a second.

This circuit is fitted into a small plastic box attached to the rear of the ING Time Service patch panel and outputs directly to the GPS 1mS/Sec and 1mS/Sec UTC patch panel BNC connectors as well as driving the fibre optic transmitters.

The SULZER Quartz Oscillator

Since the introduction of the GPS-8000, the SULZER high stability quartz oscillator no longer supplies the 100KHz phase reference for the Linear Phase Recorder bank. It is kept as a backup 100KHz frequency reference in case of failure of the GPS-8000. It is left continually running and connected to Linear phase recorder 4 (input A2-sine) so that measurements of phase shift errors between itself and GPS can be monitored occasionally.

n.b. If the SULZER is used to re-calibrate drift on the HCD oscillators, the 100KHz output from the GPS 8000 supplying the A1 inputs via a BNC T' connector on the linear phase recorder bank will first need to be disconnected. The cable from the SULZER oscillator can then be plugged into the T' connector. It should be noted that the 100KHz signal from the SULZER is a SINE wave thus the switches on the LPR's will need to be placed in the Sine' position for input A2 selection and the co-axial link cables moved from the A1 inputs across to the A2 inputs.

Historical Note:

This oscillator along with a bank of others was originally used at the RGO (Herstmonceux) for maintaining GMT (now known as UTC) in the UK until the introduction of Caesium Beam Atomic clocks in the latter part of the 20^{th} century.

Linear Phase Recorders

These are occasionally used to measure the rate of drift over a long period of time of the HCD quartz oscillators within the RGO digital clocks. The phase reference signal is a 100KHz TTL square wave derived from the GPS-8000 or the SULZER quartz frequency standard, (but see above).

The 100KHz square wave output from any RGO digital clock can be phase compared against the reference. Any change in phase *i.e.* oscillator drift, will show up as a +/- movement of the meter needle over a period of time. A provision is included for driving an external 0-1mA DC strip chart recorder of resistance up to 500 ohms.

Front panel push buttons allow for the checking of the meter and the chart recorder's zero and full scale settings. A locking toggle switch enables the chart recording to be kept clear of either the 100 > 0 or 0 > 100 changeover area if a particular record is under scrutiny.

On the rear panel, three BNC inputs are provided: A1, A2 and B. The A1 and A2 inputs are switch selectable for either a sine or square wave TTL input, the A2 inputs being used for sine wave. *i.e.* When using the SULZER as the phase reference.

The 100KHz reference signal from the GPS 8000 is fed in parallel using BNC `T` pieces and co-axial links to the A1 inputs of LPR's 1,2 and 3 with the switches in the TTL position. The **B** input receives the 100KHz TTL signal to be phase monitored from a selected RGO digital clock.

n.b. To monitor the SULZER, the GPS reference is fed to the **B** input socket, with the 100KHz output from the SULZER going to the A2 socket; switched to SINE.

LPR allocation (from left to right) is:

- 1. **INT** HCD oscillator phase monitoring
- 2. WHT or JKT HCD oscillator phase monitoring (* see note below)
- 3. Spare unit
- 4. **SULZER** oscillator phase monitoring

A small two pin connector (EXT) provides an output for the chart recorder. The LPR's are powered from the ERSKINE +28V battery supply via a DC power distribution panel mounted in the rear of the right hand cabinet.

NOTE

* The use of a Linear Phase Recorder measuring the HCD oscillator drift rate of either the WHT or JKT digital clock requires the remote 100KHz signal to be put onto the site fibre optic cable normally used for sending the 1mS/Sec pulse from the remote time service back to the CTS.

The instantaneous millisecond error measurement using the MARCONI timer/counter cannot be used when a Linear Phase recorder is measuring HCD oscillator drift from either the WHT or JKT RGO digital clock.

RUSTRAC Chart Recorders

Three RUSTRAC chart recorders are mounted below the linear phase recorder bank. These can be connected to any LPR by moving the link cables between the EXT connectors.

The chart rate is 1 inch per hour and the paper roll will record one month's of data. The full scale deflection (FSD) of the RUSTRAC recorder is 0 to 10uS across the paper.

Using the RUSTRAC recorder, a *trend* is displayed after a period showing the rate and direction of drift of an HCD oscillator. A well adjusted oscillator will show as a straight line plotted after several days with very little deviation. Careful and methodical adjustment of the multi-turn dial on the HCD oscillator unit is required to achieve this.

Refer to HCD Oscillator calibration section to see how this is done.

DX300 HF radio receiver

With the introduction of the GPS 8000 satellite clock (*circa* 1990), the HF receiver serves only as a backup system for receiving time signals within the short wave bands. See the Appendix section for more information.

n.b. Since the erection of the ING met. mast, there is NO outside aerial connected to this receiver. However, the cable with its 'UHF' connector is still there and can be found under the solar screen near the met. mast. A dipole antenna with feeder rolled onto a reel is available if needed. This is kept in the Time Service drawer in the INT CLIP centre.

TIME SERVICE FIBRE OPTIC LINKS

To allow remote clock synchronisation to UTC and to monitor the rate of HCD quartz oscillator drift in the **WHT** and **JKT** RGO digital clocks, those time services are linked back to the CTS in the INT clip centre via fibre optic (FO) cables. Each cable carries **four** fibres. One pair is used for the ING Time Service.

n.b. The second pair WAS used for the ING DECNET service. However, since the installation of the 10BaseT distributed network, new site fibres were laid to accommodate this. The other pair now serve as backup fibres.

The time service FO cables carry the following signals:

WHT

- 1mS/Sec signal from the GPS 8000 to the WHT time service (clock synchronisation)
- 1mS/Sec signal from the WHT time service back to the CTS. (UTC drift monitoring)

JKT

- 1mS/Sec signal from the GPS 8000 to the JKT time service. (clock synchronisation)
- 1mS/Sec signal from the JKT time service back to the CTS. (UTC drift monitoring)

n.b. It should be noted that due to the long cable lengths between buildings, a propagation delay occurs which should be taken into account if microsecond setting accuracy of UTC for the WHT and JKT times services is required. These being:

- Delay to WHT = $2.90 \ uS$
- Delay to JKT $= 0.95 \ uS$

Site Time Service Fibre Optic Cables

Two heavy duty armoured FO cables run from wall mounted termination boxes in the INT clip centre. These drop down through the main cable duct and pass along cable trays in the Electrical Distribution Room and Services Duct on the ground floor and leave the west side of the building under a manhole marked **RGO** inside the solar screen. The two cables split in a second manhole also marked **RGO** near the fire escape. One cable runs up the duct beside the steps up to the JKT. The other cable duct follows the road past the generator house and up to the WHT.

CTS Fibre Optic Interface Box

Standard SMA fibre optic to TTL transmitters and receivers from RS Components are used to interface the 1mS/Sec signals from the GPS-8000 and the remote time services onto the site FO cables. The left hand rack of the CTS contains the FO interface box (see Figure 2) One tx/rx pair is used for the WHT fibres, the other pair for the JKT. An extra pair was reserved for the Carlsberg Meridian telescope , but now serve as spares.

SMA FO patch cables pass under the floor from this box to the wall mounted WHT/JKT FO termination boxes. Connections to the time service patch panel is made using co-axial cable links with BNC connectors. The FO transmitters are daisy-chained together with BNC `T' connectors and co-ax cable links. The 1pss signal from the GPS 8000 (after first being converted to a 1mS/Sec pulse by the Pulse Generator) drives the FO transmitters.

A small diecast box mounted nearby contains a voltage regulator and associated circuitry to supply +5 volts for the FO TXR's and the Pulse Generator This is derived from the +28 volt supply available from the power distribution box.



WHT and JKT FO - TTL interface boxes use the same circuit as above, but with one TX/RX pair



Figure 2 Fibre optic interface box circuit

JKT Time Service Fibre Optic Cables

The armoured FO cable enters the building on the north side and comes up into the electrical power intake room in the basement. Due to an error made in cable length calculation (was too short), a FO link was made in the basement using in-line SMA connectors. These are fitted into a conduit box marked FIBRE OPTICS.

Due to the large diameter of the armoured cable and problems in passing this through the conduit, the cable was reduced in diameter by removing the outer sheath and the armouring.

The cable continues up to the CLIP centre in a conduit to a wall mounted FO SMA termination box. FO patch cables from this box pass into the time service/networking rack cabinet and connect into a small box which contains the FO to TTL transmitter and receiver.

BNC to PHONO link cables carry the signals to and from this box to the CLOCK SYNC IN (UTC) and 1mS/Sec (out) connectors on the rear panel of the digital clock.

The +5 volt supply for the FO TXR's comes directly from the JKT digital clock via a miniature 2 pin connector.

WHT Time Service Fibre Optic Cables

The armoured fibre optic cable enters the building on the north side and comes up into the power intake room on the ground floor. The cable then passes through floor ducts into the aluminisation area and runs up the cable tray to the ceiling and into the control room. The FO cable continues under the floor tiles behind the blue cabinets, through the terminal area finally terminating in a box with SMA connectors under the floor in the computer room.

FO patch cables from this box pass under the floor into the rack cabinet containing the Time Service, DEC ALHA TCS computer and the system CAMAC crate. These connect to a small box mounted at the top of the cabinet which contains the FO to TTL transmitter and receiver.

BNC to PHONO link cables carry the signals to and from this box to the CLOCK SYNC IN (UTC) and 1mS/Sec (out) connectors on the rear panel of the digital clock.

The +5 volt supply for the FO TXR's comes directly from the WHT digital clock via a miniature 2 pin connector.

WHT TDS

Below the RGO digital clock is the TDS crate (Time Distribution System). This was used to generate UTC over the WHT UTILITY NETWORK to the Dutch (MKII) CCD controllers. As these have now been replaced with SDSU CCD controllers, this unit is now redundant.

n.b. As it is still uncertain if accurate time is needed for instrument control in the future, it has been left connected.

THE RGO DIGITAL MODULAR CLOCK

The drawing below shows the overall layout of the digital clock.



Figure 3 RGO Digital Modular clock layout

A description of each module follows :

HCD precision quartz oscillator

All clock operations are derived from this unit. The oscillator itself consists of a fifth overtone 5MHz quartz crystal resonator manufactured by HCD Research Ltd. This is a specially selected HCD 125 unit having an ageing rate of less than 1×10^{-10} per day after 90 days operation. The oscillator is factory sealed and is mounted on a module also made by HCD together with circuits providing isolated outputs at 10MHz (sine), 5MHz (sine) and 1MHz (CMOS levels). Power at +28V is directly connected to the rear of the module via a 9 way `D' type connector.

IMPORTANT : The power to the clock should never be removed else long term stability of the quartz crystal oscillator will be lost

Sidereal Rate Generator

The SRG module is driven with the 1MHz oscillator signal and generates a pulse train at the rate of 1.002737 *** MHz to drive the ST clock module. The three least significant digits are adjustable manually from a thumb wheel switch mounted on the front panel to accommodate for future changes in the rate of the rotation of the Earth. The current figure for setting these switches is 909 (2002) Info from : <u>http://tycho.usno.navy.mil/sidereal.html</u>

UTC Digital Clock

The UTC clock module consists of the following sub-modules:

- Mother board with digital clock circuitry.
- Divider circuits (Daughter board).
- Signals and Codes (Daughter board).
- Front panel board with LCD indicators and controls mounted integrally.

The basic input to the module is a 1MHz square wave signal from the quartz oscillator. This frequency is then divided down to provide all the frequency services which are needed by the digital clock circuits. The signals and codes circuit provides the time signals which are available from the rear panel connectors.

On the front panel are the following buttons and displays:

- Six digit LCD display for hours, minutes and seconds
- Six push buttons to set the time display
- Four digit LCD display for the day number (0 to 365/366)
- Three push buttons for setting the day number
- Four digit LCD display for the year
- Two push buttons for setting the year (units and tens only)
- Five push buttons for ADVANCING the time by preset amounts
- Five push buttons for RETARDING the time by preset amounts
- Bank of thumbwheel switches for setting the leap year/leap second

A STOP button is also fitted and a SYNC ENABLE button to allow the clock to be synchronised to an external time signal. The 1mS/S pulse derived from the GPS-8000 being used for this.

The buttons for advancing or retarding the clock have the following rates:

100mS 10mS	1mS	100uS	10uS
------------	-----	-------	------

The leap year/leap second switches allow for these events to be preset **BEFORE** the event occurs.

ST Digital Clock

The (Local) Sidereal Time clock module is driven from the output of the SRG module at 1.002737 (909) MHz. The internal circuits are basically the same as the UTC module, but with the following omissions:

- The four digit LCD display for the year and associated push buttons.
- The thumbwheel switch assembly for leap year/leap second selection.
- The IC's normally associated with the items list above.

Standard Time Distribution Module

Two of these modules are fitted into the clock mainframe. These are fed from the UTC and ST modules and provide a range of frequencies and signals suitable for general time distribution within the local area of the time service.

The large WHARTON time display boxes for UTC and LST located in the control rooms of each telescope are driven from an IRIG signal from these modules.

n.b. In recent years, the WHARTON display have been replaced with free running UTC / LST digital clocks, so the Standard Time Distribution modules to all intents are redundant.

Computer Frequency Distribution Module

This module supplies frequencies relative to UTC required by the TCS computer and CAMAC. These signals are available both from the rear panel BNC and PHONO sockets and the three 132w *Hughes* connectors. The frequencies available from the *Hughes* connectors are:

- 1MHz A general purpose clock signal supplied to the CAMAC ED012 Pulse Generator and the LP34 Millisecond Generator modules at ALL telescopes and to the MARCONI servo electronics crate in the WHT
- 1KHz Was used for JKT photometer timing, but is now redundant.
- 50Hz Not used now by TCS
- 10Hz Not used now by TCS
- **1mS/Sec** Required by the CAMAC **LP34** Millisecond Generator. It is also used as the reference signal from the time service (RGO clock) that can be monitored at the CTS.

Other frequencies are also available, but only from the rear BNC and phono sockets. The 100KHz signal for oscillator phase checking being one of these.

Computer Time Distribution Module

These modules supply UTC time which is distributed to the TCS computer (now a DEC ALPHA) via CAMAC in parallel BCD format. Although there are three of these modules, only one is used. The other two serving as spares.

When the clock was originally designed, the requirement was to supply time to the Instrument Control System (ICS) which also used CAMAC and to a backup ICS computer/CAMAC system used for engineering testing. <u>This is no longer the case</u>,

The BCD data from these modules are:

- SECONDS (in units and 10's)
- MINUTES (in units and 10's)
- HOURS (in units and 10's)
- DAY OF YEAR (in units, 10's and 100's)
- YEAR (in units and 10's)

n.b. The '20' (century) as displayed is generated internally by pre-settable links and is NOT sent to the TCS.

A delayed 1pps is also generated to clock the above information into CAMAC. These signals (along with those from the Computer Frequency Distribution module) are fed to three 132w *Hughes* connectors on the rear panel. One connector for each CTD module.

The drawing below shows the interconnections between the various modules. Detailed circuit diagrams and description of operation can be found in the **INT Technical Documentation manuals**: **73** and **74**.



Figure 4 RGO digital clock block diagram

POWER SUPPLY

The RGO digital clocks operate at 28V DC. This supply coming directly from an ERSKINE constant potential battery charger. These are located in the electrical power intake rooms of each telescope building. The clock is connected directly across the battery bank. If the mains charging fails, the batteries will keep the clock going for approximately 24 hrs. *n.b.* Less time for the CTS as the LPR bank and GPS8000 also use this supply.

Servicing the ERSKINE battery charger

The 28V DC power input to the clock is via a 3 pin MIL type connector. There are two of these.

The reason being that when the ERSKINE battery units are serviced, the clock can be maintained by connecting another 28V DC source to the spare connector **<u>BEFORE REMOVING THE NORMAL SUPPLY.</u>**

The 28V DC supply connectors are protected by power diodes to prevent voltage back feeding. This allows a backup PSU to be connected with the normal supply from the ERSKINE still in situ.

A 'tool box' containing two 12v dry batteries complete with a flying lead fitted with a time service power connector is available for this. This is kept in the INT Electronics workshop store. It is important that the battery box is checked and re-charged before use. For added protection, the battery box should be 'floated' across a bench PSU with the voltage adjusted to provide a trickle charge to the batteries.

IMPORTANT NOTE: If the HCD master oscillator STOPS, it can take up to 90 days to re-achieve stability

TIME SERVICE DISTRIBUTION TO CAMAC

The drawing below shows the interconnections. This is the same for ALL telescopes.



Figure 5 Time service to CAMAC connections

A pair of multi-core cables taken from one of the clock's 132w *Hughes* connectors terminate in a <u>Time Service</u> <u>Computer Distribution Box</u>. These boxes are mounted near the **SYSTEM** CAMAC crates at each telescope.

This box is fitted with two 58 way *Hughes* sockets labelled A and B. Socket A carries the hours, minutes and seconds BCD data; socket B the day number and year BCD data. Links are made from these connectors via short twisted pair cables to CAMAC.

This box is also fitted with LEMO sockets which carry signals:

- 1MHz
- 1*KHz*
- 50Hz
- 10Hz
- 1mS/Sec

related to UTC from the time service needed by the TCS. n.b. Only the 1MHz and 1mS/Sec (1pps) are used now.

CAMAC modules associated with the Time Service

n.b. The information below applies to ALL telescopes.

PR2402 - Dual parallel input register (Address: B0 C0 N10)

The TCS reads in UTC from the time service via this module. *hh:mm:ss* data in BCD format is supplied to Input A. The *day of year* number and *year* data to Input B. A delayed 1pps from the clock is used as a strobe pulse to read the data into this module.

LP34 - Millisecond Generator (Address: B0 C0 N11)

The TCS also needs to read milliseconds related to UTC. This is done using the LP34 module. It is essentially a divider/counter. Firstly, it divides the 1MHz signal from the time service to produce 1mS pulses. These pulses are then passed to a binary counter with a range of 1023. The outputs from the counter are then fed to two registers. One register is updated every millisecond and therefore provides *current time*. The other register is strobed by an external 20Hz pulse from the ED012 module and provides *staticised time*. The TCS reads the strobed register within the LP34 module containing the staticised count. The computer now has time accurate to 1mS when the encoders were last read.

ED012 - Programmable Pulse generator (Address: B0 C0 N8)

This module provides the CAMAC system timing (LAM's) and a clock (CAMCLK) to staticise the encoders. This module allows the sampling frequency to be chosen to suit the telescope servo response.

The division ratio is set to give a system clock of 20Hz (50mS). Although this clock is synchronised to the time service (derived from the 1MHz signal), it is not necessarily synchronised to the 1mS/Sec pulse. It could start up with any phase relationship unless the divider module was enabled by the computer at a specific time. The result of not phasing time and encoder strobing is that there may be an equal or less than 50mS error of indeterminancy of telescope position on startup.

See the <u>CAMAC</u> documents for more detailed information.

FAULT FINDING ON THE RGO DIGITAL CLOCKS

The RGO clocks are generally very reliable and only require the occasional push of the SYNC buttons to bring ING time in step with UTC. The rate of drift is very small, usually less than 1millisecond a month. When the drift is greater than this value, the clock's master HCD quartz crystal oscillator can be trimmed to correct for this.

IMPORTANT NOTE - SPARES

It should be noted that when the Carlsberg Meridian telescope moved over to a PC based TCS several years ago, there is now <u>a spare RGO clock</u> kept in the store on the second floor of the INT. However, the clock rack is NOT compatible with the ING RGO clocks as the rear panel connectors are non standard. Also the modules marked MERIDIAN SPECIAL are of no use. All other modules are compatible.

There are three **Computer Time Distribution modules** in each clock mainframe. The old Perkin Elmer TCS/ICS required two of these modules. Since having moved to different ICS computers, there are now TWO spare modules in each RGO clock.

The minimum requirement for a functional clock are as follows:

- 1. HCD oscillator unit
- 2. UTC digital clock module
- 3. Computer Frequencies Distribution module
- 4. Computer Time Distribution Module (one needed)

The sidereal time from the ST module is used only to drive the Wharton time display wall boxes, this is unimportant for telescope operation.

<u>A KNOWN PROBLEM</u> is that the small ceramic plate chip decoupling capacitors can break down and drop the resistance between the supply and ground rails to a low value. The effect of this is either the circuit fails or the +15 or +5v fuse blows.

If a time service is SHOWING the time, but the computer <u>CANNOT READ IT</u> then suspect one of the following:

- A faulty Computer Time Distribution module.
- A faulty CAMAC PR2402 parallel input register module
- The 5v PSU within the clock or possibly a blown fuse on the rear panel.

If for some reason the spare UTC clock module is faulty, it is possible to replace a UTC module with the ST module in the adjacent slot. *n.b.* <u>The TCS requires the YEAR value and the ST module cannot supply this information.</u>

TCS Software support will be needed to modify the program to allow the DEC ALPHA to overcome the problem of not being able to read in the year value from the Time Service. This has been done in the past and a 'fix' is available.

If software support is available; to use an LST module in place of a faulty UTC module, proceed as follows:

- Remove the UTC module from it's slot and replace with the ST module. The power does NOT need to be switched off for module replacement and if done would seriously degrade the clock's stability.
- Set up UTC on the ST module. (Set your wrist watch as accurately as possible from another time service)
- Set up the correct DAY NUMBER with the associated buttons
- Push the SYNC button on the ST module to synchronise the seconds
- Check with you watch that the UTC is still correct
- <u>Get the TCS software changed to read the year value.</u>

REGULATION AND CALIBRATION OF THE ING TIME SERVICE

This involves three operations:

1. Once a week

Check the rates of drift between the INT, JKT and WHT RGO clocks in relation to the UTC reference (GPS 8000) and re-synchronise if needed.

2. When required

Re-calibration of the RGO clocks HCD quartz crystal oscillators.

3. When required

Presetting the clocks for a LEAP YEAR or LEAP SECOND insertion.

Synchronising the INT RGO clocks to UTC using the GPS 8000

After a period, the HCD oscillators will drift due to crystal ageing and will either lose or gain time relative to UTC. The rates will be different depending on oscillator calibration and characteristics. This factor cannot be easily corrected for.

To enable the RGO clocks to be monitored and re-synchronised to UTC, two signals are available. These being:

1. To the RGO clocks

A 1mS/Sec pulse from the CTS (GPS8000) going to the CLOCK SYNC IN connectors on the RGO clocks and used for re-synchronisation.

2. From the RGO clocks

A 1mS/Sec pulse returning to the CTS for monitoring purposes.

n.b. In the case of the WHT and JKT clocks, these signals are sent over fibre optic cables.

Monitoring

Using the MARCONI counter in the CTS, move the BNC 'T' connector between the WHT, INT and JKT 1mS/Sec connectors on the Time Service patch panel. The difference in milliseconds between UTC (GPS 8000) and an RGO digital clock can be easily seen. The values obtained should be recorded in the Time Service log book.

Re-syncing

If a significant error exists (+/- 2mSecs) then push the SYNC ENABLE button on the UTC module of the clock for one duration of the PUL SEC⁻¹ LED. This will re-synchronise the RGO clock to UTC.

IMPORTANT NOTE

For reasons unknown, the act of pushing the SYNC ENABLE button on the WHT or JKT clocks can sometimes STOP the time display. Thus, although the second rising edges are correct relative to UTC, the time can be out by whole units of seconds.

The bottom line here is to 'carry' the time with you when re-syncing the WHT and JKT clocks. Set your wrist watch (a digital one is best) to the GPS 8000 as accurately as possible. It is quite easy to obtain time better to a $1/10^{\text{th}}$ of a second on a digital wrist watch.

After re-syncing, if there is an error of units of seconds, push the $S^0 - S^1$ buttons below the LCD time display to make the seconds correct. Pushing these (or any of the time display setting buttons) will <u>fast slew</u> the appropriate LCD digits. Hold your watch up against the display and check that the time between the two is correct.

Re-calibration of an HCD oscillator

If an RGO clock is losing or gaining time rapidly (> 1 millisecond a week), this is a sign that the rate of drift of an HCD oscillator is excessive and needs to be compensated for.

As the GPS8000 uses a very stable RUBIDIUM oscillator which is constantly being corrected by GPS satellite signal reception, a signal derived from this oscillator can be used as a UTC frequency standard to make *phase* comparison checks against the HCD oscillators in the RGO clocks. The Linear Phase Recorder (LPR) bank and RUSTRAC chart recorders in the CTS are used for this.

The LPR works by comparing the phases between two 100KHz TTL signals and displaying the rate of change on a meter. Because the rate of change can be very slow, the external output from the LPR is fed to a chart recorder thus phase changes between the reference oscillator and HCD oscillator under test can be monitored over long periods.

The Linear Phase Recorders are connected in the following way:

- LPR 1 Constantly monitors the phase between the INT HCD oscillator and the rubidium standard
- LPR 2 Can monitor the phase between the WHT (or JKT) HCD oscillators and the rubidium standard
- LPR 3 Not used (spare)
- LPR 4 Constantly monitors the phase between the SULZER oscillator and the rubidium standard

The RUSTRAC recorders can be connected to any LPR by simply moving the flying lead between them. Generally, RUSTRAC 1 is connected to LPR 1 (INT) and RUSTRAC 2 to LPR 2 (WHT or JKT) *n.b.* Although there are three RUSTRAC recorders, the right hand one has a faulty coil and can't be used.

Note: The direction of movement of the pen on the chart is dependant on the way the reference and comparison phase signals are connected to the LPR. The reference phase is taken to the **A1** inputs (switched to **TTL**) of LPR's 1, 2 and 3 and the HCD oscillator under test taken to the **B** input (TTL only). A movement of the pen from LEFT TO RIGHT indicates that an RGO clock is LOSING time relative to UTC.

INT - HCD Oscillator adjustment

- Put a chart paper roll in the left hand RUSTRAC recorder, switch it on and let it run for an hour or so.
- Check the slope of the plot.
- The ideal response is a line running vertically down the chart constantly, but this is impossible to achieve.
- Adjust the dial on the INT HCD oscillator <u>a small amount</u> (*e.g.* 10 dial units) + or and check how the slope of the plot has changed.
- IMPORTANT: Record the dial settings as you make the adjustments. You can then interpolate between the values to reduce the angle of slope.

The shallower the angle of the slope, the faster the rate of phase change is between the oscillators. The direction of the slope indicates whether the oscillator under test is running FAST or SLOW relative to the UTC rubidium standard. The full scale deflection of an LPR/RUSTRAC equates to a drift rate of 10uS. See Figure 6 for more information.

WHT or JKT - HCD Oscillator adjustment

The same procedure as above is used, but with one IMPORTANT difference. <u>The 100KHz signal from either the WHT</u> or JKT time service needs to be sent to the fibre which is normally used for monitoring back at the CTS.

- At the WHT (or JKT) remove the cable with a PHONO plug going to the 1mS/Sec connector (UTC) at the rear of the clock.
- Re-connect this cable to the 'floating' PHONO inline socket lead coming from the 100KHz connector.
- Back at the CTS, plug in a link cable between the WHT (or JKT) patch panel connector and run this to the connector marked: WHT / JKT 100KHz phase. This enables the HCD phase to be compared on LPR 2
- Put a chart paper roll in the middle RUSTRAC recorder, switch it on and let it run for an hour or so.
- Check the slope of the plot after an hour. The rest of the procedure is as for the INT, but necessitating occasional trips to the WHT or JKT to make HCD oscillator adjustments.

The examples below show the sort of responses which could be obtained after 3 hours of monitoring. *n.b.* The 500 set on the dial shows the HCD oscillator FINE adjustment set to mid-range, but in practice this would never be the case.

The chart on the left shows a NEGATIVE rate of oscillator drift of 10uS an hour which if not compensated for would accumulate to ~ -1.7 mS a week. This is severe and the oscillator rate would need increasing to reduce this value.

The example on the right shows a POSITIVE rate of drift in respect to UTC of 10uS in 3 hours (560us a week). Although not so severe an improvement can be made by decreasing the value shown on the dial.

Only make SMALL adjustments in the beginning (not more than 10 dial units) and recheck the slope of the chart after an hour. Aim to get the plot on the chart as vertical as possible. If the plot is running off or near to the edge of the paper, toggle the switch on the LPR to bring the pen back into the middle of the chart.

A time may come when it is NOT possible to adjust the FINE oscillator rate (max. or min. value reached). In this case it will be necessary to adjust the COARSE control. If this is required, reset the FINE control to mid range (500) and VERY CAREFULLY move the spindle a quarter turn either CW or CCW and check the slope on the chart. Always make a note of spindle direction (CW or CCW) and the distance turned; use the screwdriver slot as a guide. When the plot starts to 'open up' again, use the FINE control to refine the correction.

A week of monitoring and HCD oscillator adjustments should be enough time to bring the drift rate of an RGO clock down to a small value and allow it to run for many months without attention. *n.b.* It is normal for the HCD oscillators to 'walk around' occasionally with the plot changing direction.



Figure 6 HCD oscillator compensation

When the charts have produced a reasonably 'straight line' for a week or so, the chart recorders can be switched off from their mains sockets at the bottom of the right hand cabinet.

If either the WHT or JKT oscillator was re-calibrated, remember to disconnect the 100KHz link cable and plug the PHONO lead back into a 1mS/Sec (UTC) to enable weekly checks at the CTS.

Leap Year and Leap Second insertion

Presetting for a Leap Year and Leap Second insertion is controlled by the bank of thumbwheel switches at the bottom of the UTC clock module.

Note: *The RGO clock cannot automatically change for leap year or leap second events. This must be preset BEFORE the event occurs.*

Pre-setting for a Leap Year

A normal year consists of approximately 365.25 days. Due to this accumulation of $4 \ge 0.25$ days, an extra day needs to be added every four years, a leap year having 366 days. At the time of writing, the next leap year will be 2003.

To preset the clock for a LEAP YEAR, simply change thumbwheel (1) to a 6 *n.b.* This switch has only two settings (5 or 6) and must be left on 5 if the year is normal with 365 days.

Normal year (no leap second added)

THUMBWHEELS								
1	2 3 4 5 6							
5	3	6	5	6	0			
Leap	Day of year Leap							
year	n	umbe	er	sec	ond			

Leap year (no leap second added)

6	3	6	5	6	0
Leap	Day of year			Le	ap
year	number			sec	ond

n.b. The settings for thumbwheel switches 2, 3 and 4 (Day of Year) are NOT important if the Leap Second switches, 5 and 6 are left at 60.

Leap Second insertion

Leap seconds are necessary to keep UT1 within 0.9 seconds of UTC. See the Glossary section for more details.

Notification of a LEAP SECOND insertion is sent to the ING (the software group) in advance from the International Earth Rotation Service (IERS) in Paris in monthly bulletins. <u>http://maia.usno.navy.mil/</u>

In recent years, a leap second has been inserted at midnight on the 30th June. However, the IERS may decide this needs to be done on the 31st December. The present trend is that the rate of rotation of the Earth is slowing down in respect to TAI therefore requiring a POSITIVE leap second to be inserted. At the time of writing (July 2002), NO Leap second is required.

When a Leap Second notification is sent, it is advisable to preset the thumbwheel switches on the ING digital clocks in the INT, JKT and WHT well in advance.

Set thumbwheel switches 2, 3 and 4 to the **Day of Year** number when the Leap Second will be inserted and change the **Leap Second** switches to read **61**. This will insert one second at 00:00:00 hrs UTC.

IMPORTANT: Once the event has occurred, remember to return the leap second thumbwheel switches back to 60.

Examples:

Leap second to be inserted on the 30th June (normal year)

5	1	8	1	6	1
Leap	Da	y of y	Le	ap	
year	number			sec	ond

Leap second inserted on the 31st December (normal year)

5	3	6	5	6	1
Leap	Da	y of y	Le	ap	
year	number			sec	ond

Leap second inserted on the 30th June (leap year)

6	1	8	2	6	1
Leap	Da	y of y	Le	ap	
year	number			sec	ond

Leap second inserted on the 31st December (leap year)

6	3	6	6	6	1
Leap	Day of year			Le	ap
year	number			sec	ond

APPENDIX

Radio Time Services

In the event of the GPS8000 failing, the DX300 HF receiver in the central time service rack can be used for receiving time signals transmitted on the short wave bands. The radio time services best received in La Palma are:

- Callsign **RWM** on 14.996Mhz (Moscow, Russia) mode CW (Note 1) Travel time from transmitter to La Palma = 18mS
- Callsign **EBC** on 12.008Mhz (Cadiz, Spain) mode AM (Note 2) Travel time from transmitter to La Palma = 4.5mS

Note 1: This time service is available 24hrs, but second pips are transmitted only between minutes 10 to 30 and 40 to 60 in each hour. The remaining 20 minutes being either silent or just a steady carrier. As the mode of transmission is CW, the lower right hand control on the DX300 must be set to USB to resolve the pips as audible tones.

Note 2: This time service is only available between 10:00 and 10:25 hours daily. As the travel time is only 4.5mS this would be a better choice to use as errors in measurement due to signal propagation are minimised. However, there is often a strong commercial broadcasting station on this frequency which can make good reception and thus measurement very difficult. As the mode of transmission is AM, the lower right hand control on the DX300 should be set to that mode.

The travel time for the signals to arrive at La Palma are calculated on a ground wave signal travelling from point to point along the Earth's surface. In practice, the mode of propagation will be via ionospheric reflection (skywave), but this would be very difficult to calculate as this varies between day and night and the time of the year. The errors involved would be in the order of 10's of kilometers. This would add a few microseconds to the ground wave calculations and are of no significance as the best measurement we can expect from a short wave transmission is to 1 or 2 milliseconds.

Synchronising an RGO clock to UTC using the DX300

The Digital storage oscilloscope in the Central Time Service rack is best used for making these adjustments. To get reliable triggering on the MARCONI counter-timer is very difficult.

The example given is using the **RWM** transmission on 14.996MHz as this is available 24 hours albeit that there are unusable periods within each hour. (see Note 1)

Note : There is no permanent aerial on the roof of the INT connected to the DX300 (since the erection of the Met frame). If the DX300 is used, it is necessary to connect the dipole antenna (kept in the Time Service filing cabinet in the CLIP centre). String out the dipole antenna in roughly a NW/SE direction from a suitable point and connect up the UHF connector on the feeder reel using an in-line UHF barrel connector to the antenna cable (fitted with a UHF plug). The cable can be found under the solar screen near the Met. frame.

Back at the CTS in the INT CLIP centre, do the following:

- Connect the **A channel** of the oscilloscope to the time service to be calibrated *e.g.* The 1mS/Sec pulses from the WHT, INT or JKT clock.
- Connect the **B** channel of the oscilloscope to the BNC connector labelled **HF radio** on the patch panel.
- Tune in the DX300 receiver to the **RWM** transmission on **14.996MHz**. You need to peak up both the preselector and main tuning dials to get the strongest signal. The mode switch needs to be set to USB.

- Provided you haven't found a period of silence or just carrier (see Note 1) you will hear either regular second pips or 'punctuated' second pips with some modulation between them. This is un-important, you can use either signal.
- With the oscilloscope **SYNC set to channel A**, the time signal should appear as a burst on channel **B** with the 1mS/Sec pulse from the clock occurring at the left-hand edge of channel **A**.





In reality, the time signal will not be a clean signal as shown in the diagram, usually it is going up and down as the signal strength changes or sometimes fading completely into the noise!

- If UTC(M) (measured) is on top of UTC, this value should be around 18mS RWM (or 4.5mS EBC). If these values are significantly different then push either the 100's, 10's or 1mS ADVANCE or RETARD buttons on the UTC clock module until the offset shown on the oscilloscope is correct. In practice it is very difficult to determine the leading edge of the time signal. Just get it as close as possible
- When using the slewing buttons, hold the button down and wait for the PULSE SEC-1 led to trigger before releasing. Keeping a button pushed will increment or decrement the time by the preset amount on every second pulse. Monitoring the PULSE SEC-1 led when operating the slewing buttons will assist with this operation.

This is somewhat difficult when the WHT or JKT clocks are calibrated against the time signal. In this case, a second person needs to be at the remote clock making the adjusts and in contact with the person via a handheld radio or the intercom who can monitor the oscilloscope.

n.b. If the time signal is strong as seen on the oscilloscope, it may be possible to use the timer/counter display which is connected in parallel also. It should show a reasonably constant value. This may dither somewhat due to changes in propagation of the time signal or signal strength. What to look for is a trend for the counter - timer to show a value of ~18mS (or ~4.5mS with EBC) with regularity.

• Once the clock is calibrated, ensure that the time is correct with another RGO clock. Pushing the 100mS slewing buttons can cause the clock gain or lose whole seconds. If this happens, push the $S^0 - S^1$ buttons below the LCD time display to make the seconds correct.

Instructions for resetting the time displays

RGO clocks

If a UTC module has been removed for repair, it will be necessary to reset the LCD displays to the correct time. Start by first setting your (digital) wrist watch to within 1 second of UTC using the time from a working RGO clock or from the GPS 8000.

Set the time display to the correct time with the associated push buttons in the order:

- Tens of HOURS
- Units of HOURS
- Tens of MINUTES
- Units of MINUTES
- Tens of SECONDS
- Units of SECONDS

The time should then be within a few seconds of UTC. Re-adjust the seconds buttons so that the displayed time is more or less in synchronism to your watch. When satisfactory, use the procedures as described previously to synchronise the seconds to UTC.

Set the DAY NUMBER and YEAR displays to their correct values with the appropriate push buttons below those displays.

Although Sidereal Time from the RGO clocks is not used, to make it correct use the ST value as displayed on the TCS Info Display window using the procedure above. *n.b.* The Info Display does not get the instantaneous time due to delays in the TCS when updating the window, but certainly for setting LST, it is more than adequate.

AWR control room clocks

These clock replacements for the WHARTON display wall boxes were <u>not quite as I intended!</u> We specified time displays that were driven from the RGO clocks (as per the WHARTON units), but ended up with a free standing UTC/LST clock driven from an internal (and NOT very precise) crystal oscillator. Looks like we're stuck with them. Very pretty, but not that accurate!

To adjust these, you need to hold the SET button whilst operating the FAST (hours) or SLOW (minutes) buttons. Get UTC time as close as possible within 30 seconds BEFORE the minute event occurs then push the SLOW button to start the minutes running co-incident with the TCS Info Display. The LST display is set in the same way.

It's a fiddle-arse task, but once done a few times you'll get the hang of it O

GLOSSARY

Brief explanation of Time Scales

UT Universal Time

This is the mean solar time used for civil timekeeping purposes and is formally defined by a mathematical formula which relates UT to Greenwich Mean Sidereal Time. This is determined from observations of stars crossing the meridian.

UT1 Previously known as Greenwich Mean Time (GMT)

Is UT corrected for the effect of small movements of the Earth relative to the axis of rotation (polar variation).

TAI International Atomic Time

Is the most precisely determined time scale for astronomical use. The scale results from analyses by the Bureau International des Poids et Mesures in Paris from atomic time standards of many countries. The SI definition of the second being:

The second is the duration of 9 192 631 770 periods of the radiation corresponding to the transition between two hyperfine levels of the ground state of the caesium-133 atom

UTC Universal Co-ordinated Time.

Since 1st January 1972, the time scale distributed by most radio time services has been based on redefined co-ordinated time (UTC) which differs from TAI by an integral number of seconds. UTC is maintained within 0.9sec of UT1 by the introduction of one second steps (leap seconds) when necessary, normally the last day of June or December at 24:59hrs.

DUT1, an approximation to the difference UT1-UTC, is transmitted in code on the radio time signals.

At the time of writing (July 2002): UTC-TAI = -32 seconds exactly

GMST Greenwich Mean Sidereal time

The interval of time between two consecutive transits of a star crossing the prime meridian of Greenwich 0° longitude.

LST Local Sidereal Time

The interval of time between two consecutive transits of a star crossing the local meridian of observation. Local mean sidereal time is computed from the current Greenwich Mean Sidereal Time plus an input offset in longitude converted to a sidereal offset by the ratio 1.00273790935 of the mean solar day to the mean sidereal day.

Sidereal time gains approximately 4 mins daily on UT. This is due to the fact that sidereal time takes into account not only the 24hr Earth rotational period, but also the rotation of the Earth around the Sun. Hence, the time recorded when a star crossing the meridian when measured the next night, will be approximately 4 minutes later.

The ING TCS computers calculate the local sidereal time (knowing the UTC and the longitude of the local meridian) and use this to staticise (read) the position encoders.